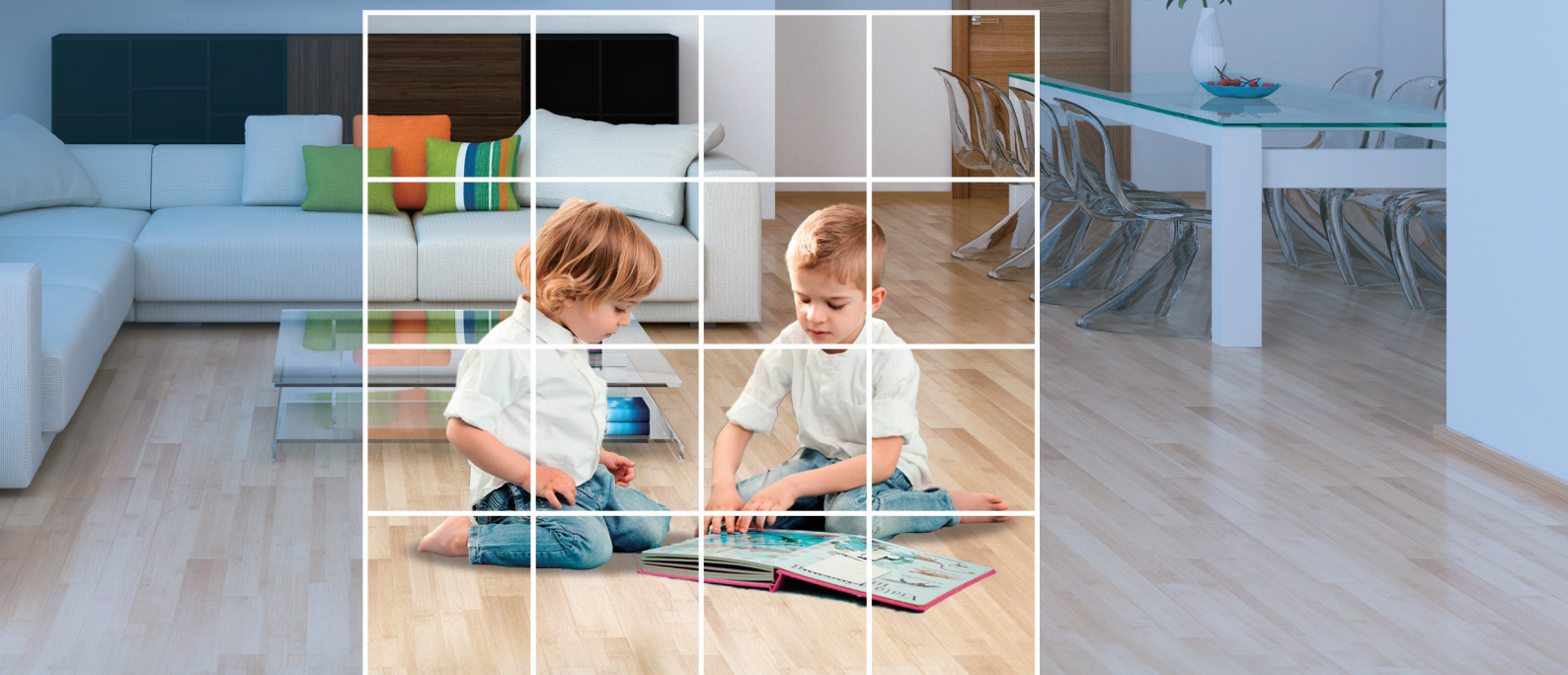


## MEMS Thermal Sensors D6T

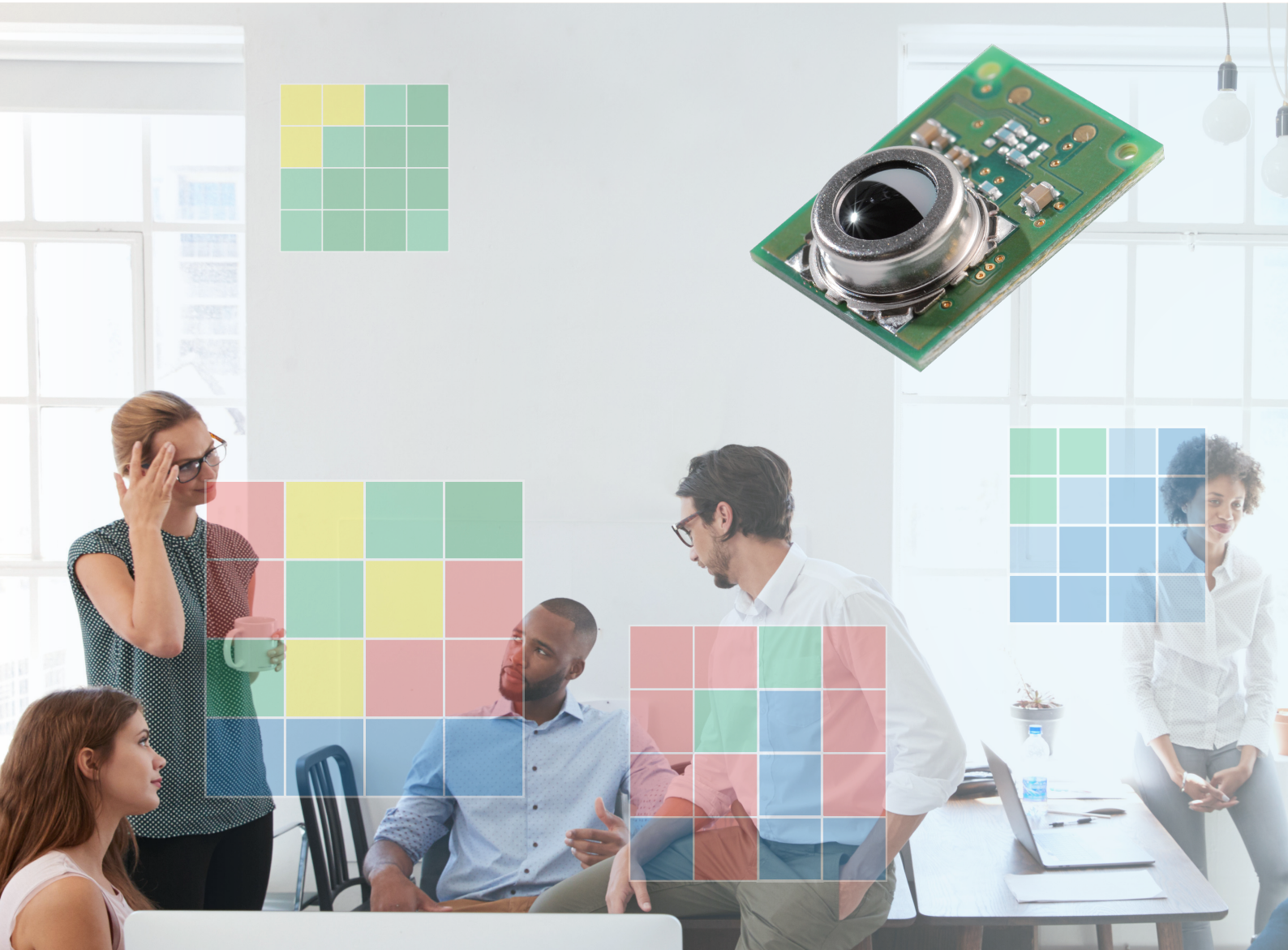


Contactless measurement  
creating energy-efficient and comfortable living spaces





# High Accuracy, Smaller Footprint, East to Work With



OMRON's unique MEMS technology allows combining thermopile elements and ASICs into one package resulting to ultra-compact footprint.

MEMS Thermal (IR\* sensor) measures the surface temperature of objects without touching them when the thermopile element absorbs the amount of radiant energy from the object.

\*IR: Infrared Ray

**Low noise**

**Achieving the highest level of SNR\* in the world \*2**

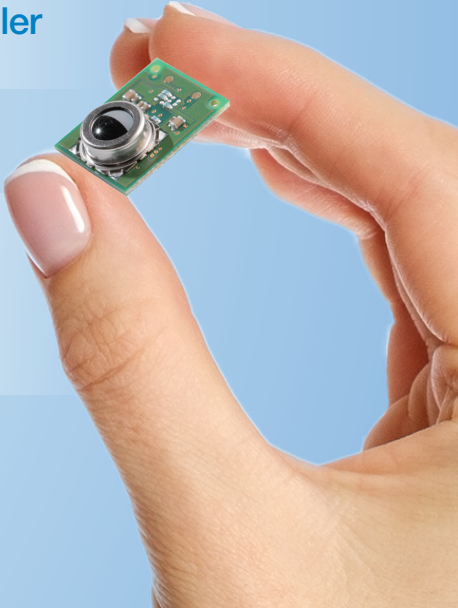
\* SNR: Signal-to-Noise Ratio. Compares the level of a signal to the level of background noise  
 \*2 As of December 2017, according to OMRON research

**Easy connection**

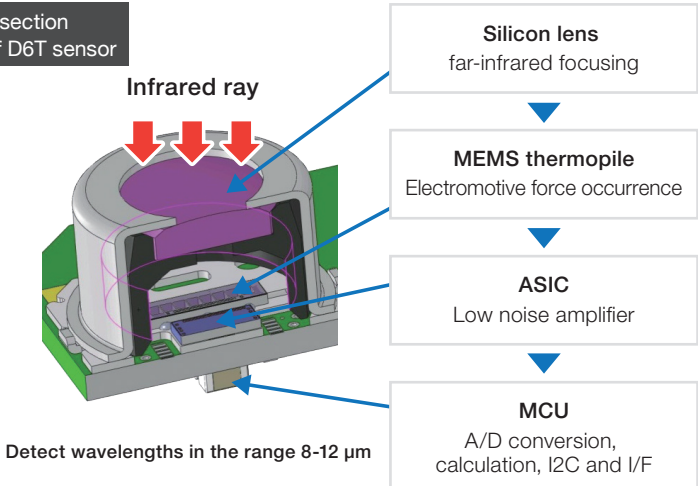
**Converts sensor signal to digital temperature output allowing easy use of microcontroller**

**Compact size**

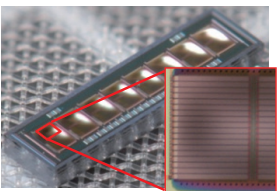
**Space-saving design, well-suited for embedded applications**



Cross-section view of D6T sensor



MEMS thermopile



Detection principle



The sensor utilizes the seebeck effect in which thermoelectric force is generated due to the temperature difference that occurs across the junction points of two different types of metal.



# Human Detection

D6T series sensors can detect human presence by sensing changes in human body temperature with respect to the surrounding temperature.



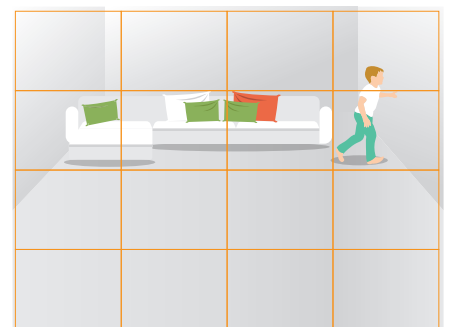
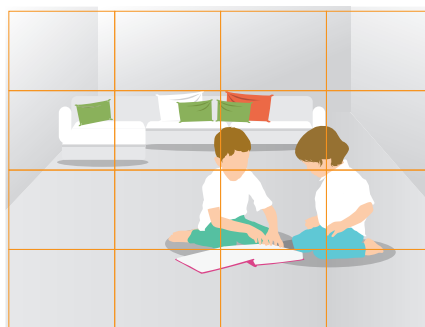
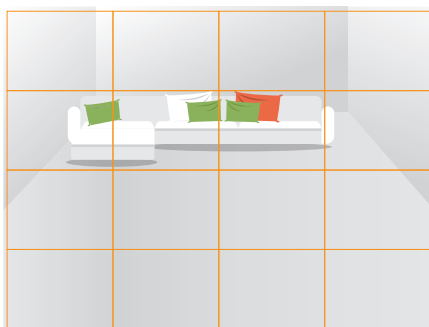
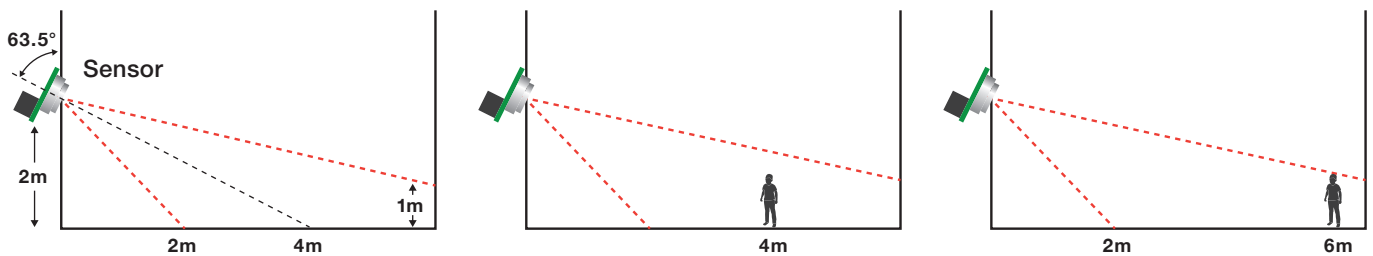




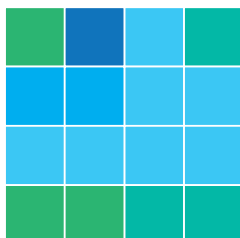
D6T application fields    Air conditioners, lighting systems, security systems, nursing care and monitoring equipment

D6T series sensors can detect the slightest temperature changes that can be used in variety of applications including energy-efficient home appliances and security systems. The sensors can also be used in the application fields of HEMS (Home Energy Management System) and BEMS (Building Energy Management System).

Installation condition    Recommended type: D6T-44L-06 (4x4-element / viewing angle: X=44.2° Y=45.7° / Object temperature range: 0 – 50degC)



Detection results of temperature distribution





# Object Detection

D6T sensors can detect objects by pinpointing the target object temperature.





D6T sensors let you measure temperature without the need to physically touch the object. This allows measuring temperature where it was not possible for contact thermal sensors due to space shortage. The sensors can be used in a wide range of applications including FEMS (Factory Energy Management System).



D6T sensor meets customer needs by providing a wide range of application support from home appliances to industrial use.



D6T application fields Industrial equipment, non-contact thermometers, refrigerators, microwave ovens, IH cooking heaters, data centers

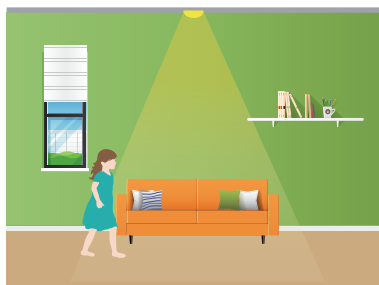
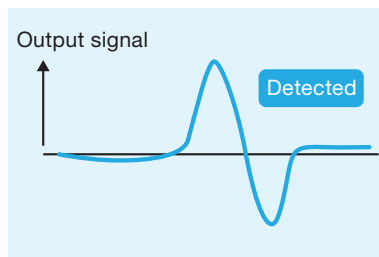


# Comparison with Pyroelectric Sensor

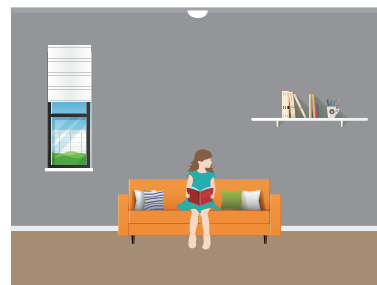
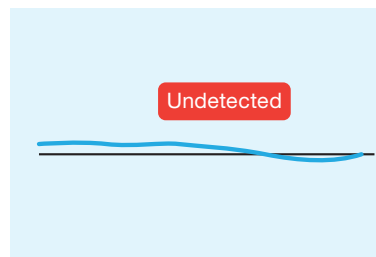
Both the pyroelectric sensor and non-contact MEMS thermal sensor can detect even the slightest amount of radiant energy from objects such as infrared radiation and convert them into temperature readings. However, unlike pyroelectric sensor that relies on motion detection, non-contact MEMS thermal sensor is able to detect the presence of stationary humans (or objects).

## Pyroelectric sensor

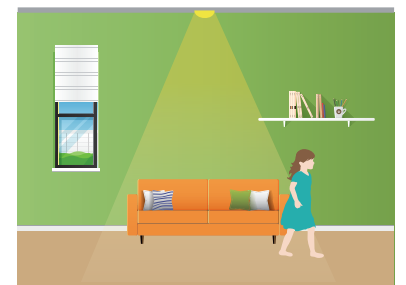
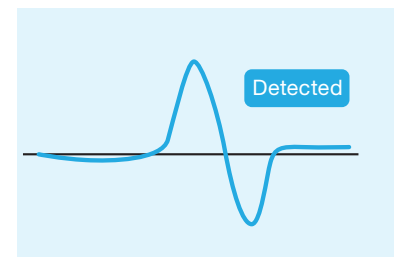
Converts temperature readings only when detecting “**temperature changes** in the radiant energy” in its field of view.



Able to detect human (object) motion



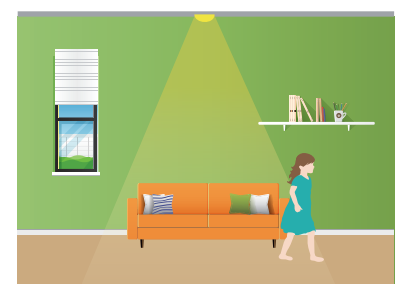
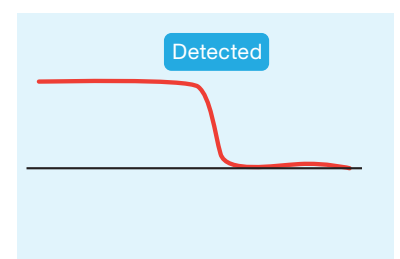
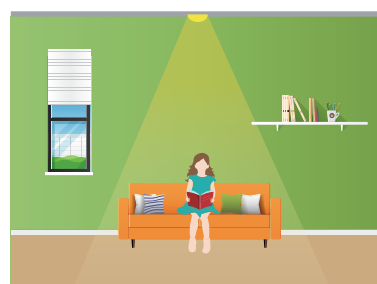
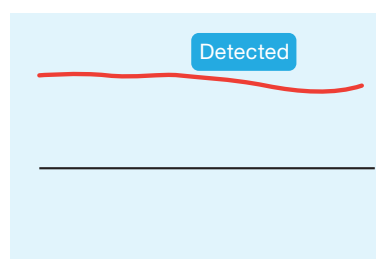
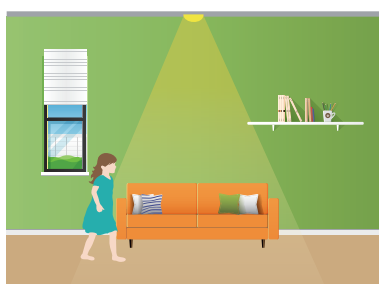
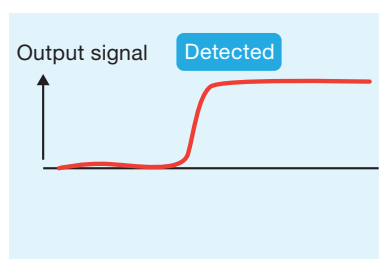
Unable to detect stationary human (object) presence



Able to detect human (object) motion

## MEMS thermal sensor (thermopile)

Converts temperature readings by “**continuously detecting** the temperature of radiant energy” in its field of view






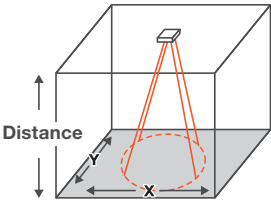
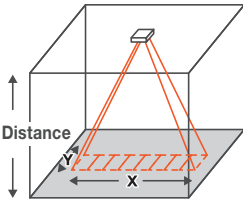
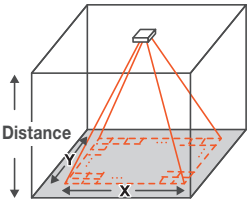
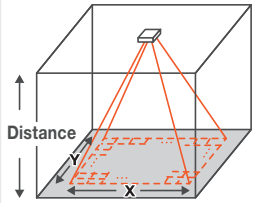


Able to detect both stationary and motion state of humans (objects).



# Viewing Angle and Measurement Area

Choose your preferred sensor viewing angle to meet your application needs.

Sensor type	D6T-1A-01	D6T-1A-02	D6T-8L-09/09H	D6T-44L-06/06H	D6T-32L-01A
Appearance					
Number of elements	1(1x1)		8(1x8)	16(4x4)	1024(32x32)
Number of elements X-direction Y-direction	X = 58.0° Y = 58.0°	X = 26.5° Y = 26.5°	X = 54.5° Y = 5.5°	X=44.2° Y=45.7°	X=90.0° Y=90.0°
Size of measurement area					
Distance 1m	X = 111cm Y = 111cm	X = 47cm Y = 47cm	X = 103cm Y = 10cm	X = 81cm Y = 84cm	X = 200cm Y = 200cm
Distance 2m	X = 222cm Y = 222cm	X = 94cm Y = 94cm	X = 206cm Y = 20cm	X = 162cm Y = 169cm	X = 400cm Y = 400cm
Distance 3m	X = 333cm Y = 333cm	X = 141cm Y = 141cm	X = 309cm Y = 30cm	X = 244cm Y = 253cm	X = 600cm Y = 600cm

\* The sizes of measurement area indicated above are for reference only.

\* The size of measurement area changes according to sensor mounting angle.



# D6T

MEMS Thermal Sensors

## High Sensitivity Enables Detection of Stationary Human Presence

- OMRON's unique MEMS and ASIC technology achieve a high SNR.
- Superior noise immunity with a digital output.
- High-precision area temperature detection with low cross-talk field of view characteristics.



RoHS Compliant



Refer to *Safety Precautions* on page 17.

## Ordering Information

### Thermal Sensors

Element type	Model	Shape
4×4	D6T-44L-06/06H	
1×8	D6T-8L-09/09H	
1×1	D6T-1A-01	
	D6T-1A-02	
32×32	D6T-32L-01A	

## Model Number Legend

D6T-□-□ □  
(1) (2) (3)

### (1) Number of elements

- 44L : 16 (4 × 4)
- 8L : 8 (1 × 8)
- 1A : 1 (1 × 1)
- 32L : 1024 (32 × 32)

### (2) Viewing angle

- 06 : X direction=44.2°, Y direction=45.7°
- 09 : X direction=54.5°, Y direction=5.5°
- 01 : X direction, Y direction=58.0°
- 02 : X direction, Y direction=26.5°
- 01A : X direction, Y direction=90.0°

### (3) Special Functions

- H : High-temperature type
- Non-display : Standard sensor

### Accessories (Sold separately)

Type	Model
Cable Harness	D6T-HARNESS-02



## Ratings, Specifications, and Functions

### Ratings

Item	Model	D6T-44L-06/06H	D6T-8L-09/09H	D6T-1A-01	D6T-1A-02	D6T-32L-01A
Power supply voltage		4.5 to 5.5 VDC				
Storage temperature range		-10 to 60°C	-20 to 80°C	-20 to 80°C (with no icing or condensation)	-40 to 80°C	-20 to 80°C
Operating temperature range		0 to 50°C	0 to 60°C	0 to 60°C (with no icing or condensation)	-40 to 80°C	-10 to 70°C
Storage humidity range		85% max.	95% max.	95% max. (with no icing or condensation)	95% max.	95% max.
Operating humidity range		20% to 85%	20% to 95%	20% to 95% (with no icing or condensation)	20% to 95%	20% to 95%

### Characteristics

Item	Model	D6T-44L-06/06H	D6T-8L-09/09H	D6T-1A-01	D6T-1A-02	D6T-32L-01A
View angle <sup>*1</sup>	X direction	44.2°	54.5°	58.0°	26.5°	90°
	Y direction	45.7°	5.5°	58.0°	26.5°	90°
Object temperature output accuracy <sup>*2</sup>	Accuracy 1	±1.5°C max. Measurement conditions: Vcc = 5.0 V (1) Tx = 25°C, Ta = 25°C (2) Tx = 45°C, Ta = 25°C (3) Tx = 45°C, Ta = 45°C				Within ±3.0°C Measurement conditions: Vcc = 5.0 V Tx = 25°C, Ta = 25°C Central 16-pixel area
	Accuracy 2	±3.0°C max. Measurement conditions: Vcc = 5.0 V (4) Tx = 25°C, Ta = 45°C				Within ±5.0°C Measurement conditions: Vcc = 5.0 V Tx = 80°C, Ta = 25°C Central 16-pixel area
Current consumption		5 mA typical		3.5 mA typical		19 mA typical

### Functions

Item	Model	D6T-44L-06/06H	D6T-8L-09/09H	D6T-1A-01	D6T-1A-02	D6T-32L-01A
Object temperature detection range <sup>*2</sup>		5 to 50°C/5 to 200°C	5 to 50°C/5 to 200°C	5 to 50°C	-40 to 80°C	0 to 200°C
Reference temperature detection range <sup>*2</sup>		5 to 45°C	5 to 45°C	5 to 45°C	-40 to 80°C	0 to 80°C
Output specifications		Digital values that correspond to the object temperature (Tx) and reference temperature (Ta) are output from a serial communications port.				
Output form		Binary code (10 times the detected temperature (°C))				
Communications form		I2C compliant				
Temperature resolution (NETD) <sup>*3</sup>		0.06°C	0.03°C	0.02°C	0.06°C	0.33°C <sup>*4</sup>

\*1. Refer to *Field of View Characteristics*.

\*2. Refer to *Object Temperature Detection Range*.

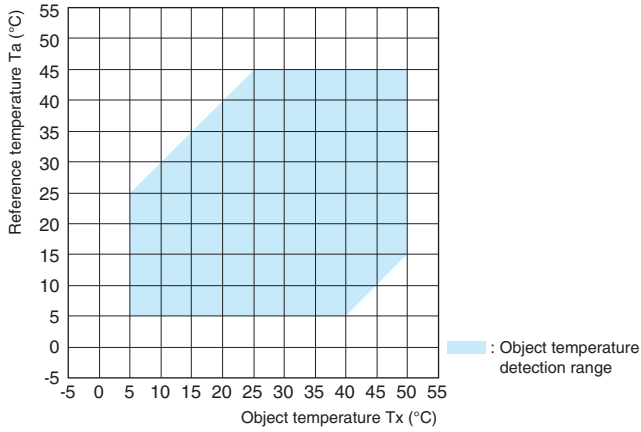
\*3. Reference data

\*4. Taken to be the average value of the central 4 pixels.

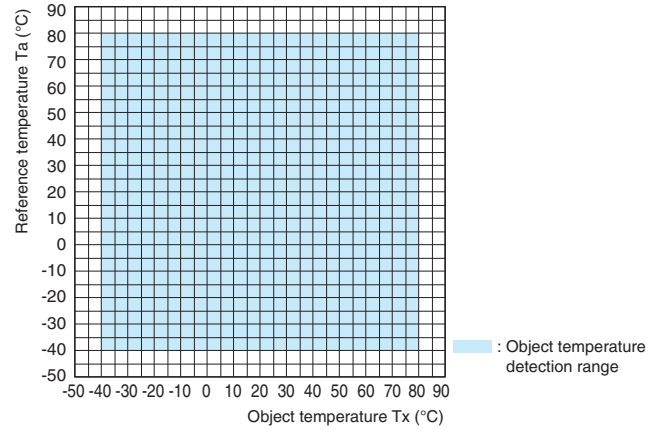


## Object Temperature Detection Range

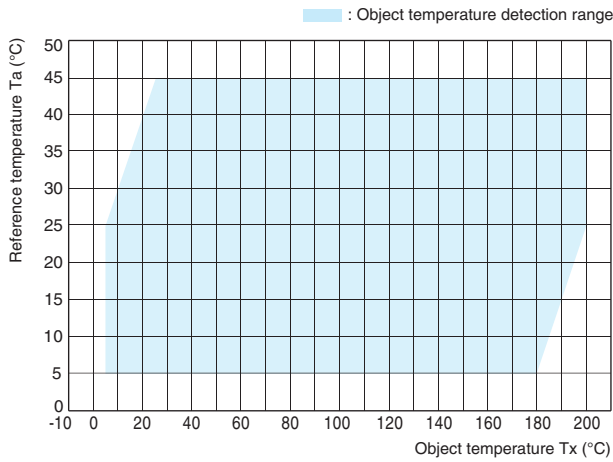
D6T-44L-06, D6T-8L-09, D6T-1A-01



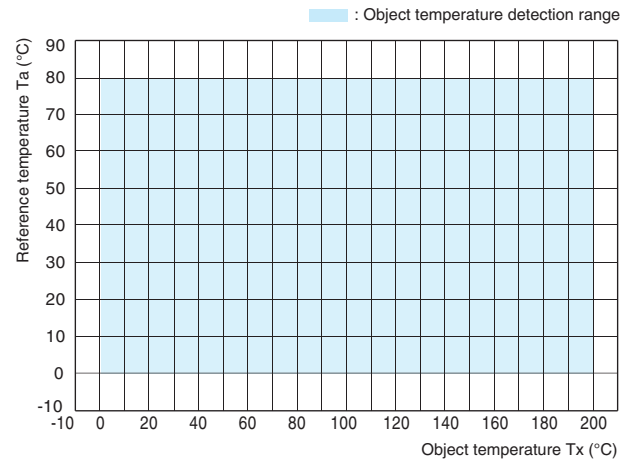
D6T-1A-02



D6T-44L-06H, D6T-8L-09H



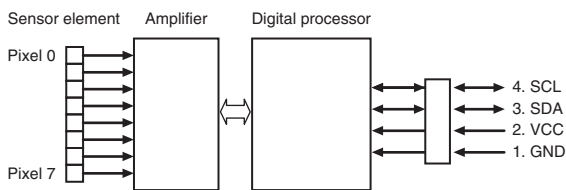
D6T-32L-01A



## Connections

### Thermal Sensor Configuration Diagram

<D6T-8L-09/09H>



Note: The D6T-44L-06/06H has pixels 0 to 15.  
 The D6T-1A-01/02 has pixel 0.  
 The D6T-32L-01A has pixel 0 to 1023.

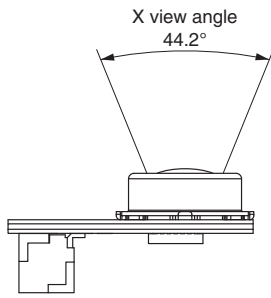
### Terminal Arrangement

Terminal	Name	Function	Remarks
1	GND	Ground	
2	VCC	Positive power supply voltage input	
3	SDA	Serial data I/O line	Connect the open-drain SDA terminal to a pull-up resistor.
4	SCL	Serial clock input	Connect the open-drain SCL terminal to a pull-up resistor.

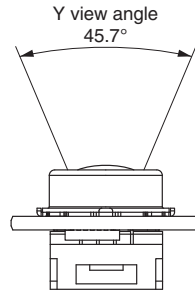
## Field of View Characteristics

### D6T-44L-06/06H

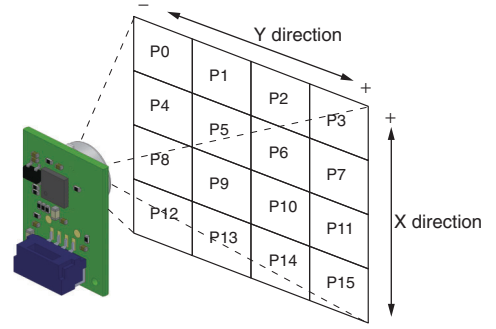
#### Field of view in X Direction



#### Field of view in Y Direction



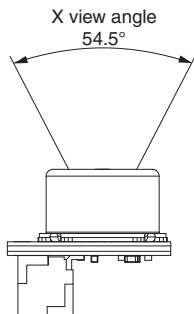
#### Detection Area for Each Pixel



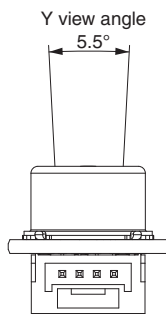
Note: Definition of view angle: Using the maximum Sensor output as a reference, the angular range where the Sensor output is 50% or higher when the angle of the Sensor is changed is defined as the view angle.

### D6T-8L-09/09H

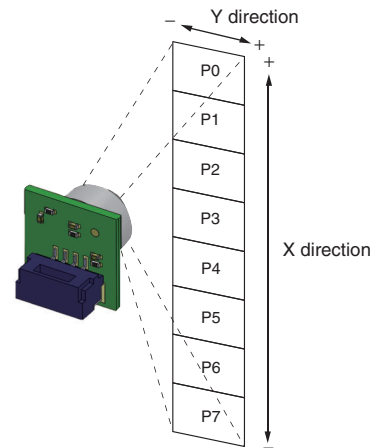
#### Field of view in X Direction



#### Field of view in Y Direction



#### Detection Area for Each Pixel

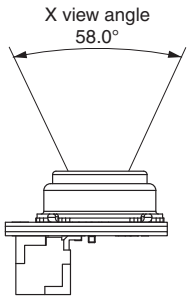


Note: Definition of view angle: Using the maximum Sensor output as a reference, the angular range where the Sensor output is 50% or higher when the angle of the Sensor is changed is defined as the view angle.

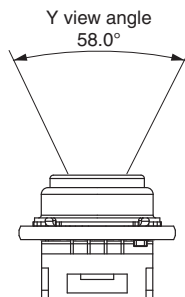


## D6T-1A-01

### Field of view in X Direction

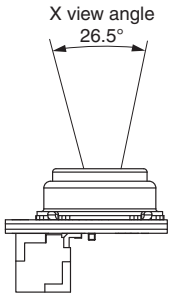


### Field of view in Y Direction

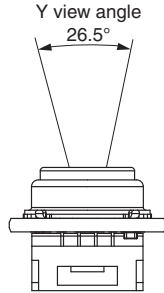


## D6T-1A-02

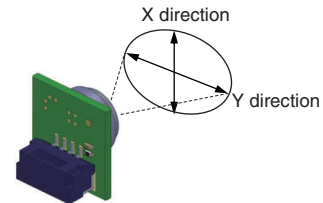
### Field of view in X Direction



### Field of view in Y Direction



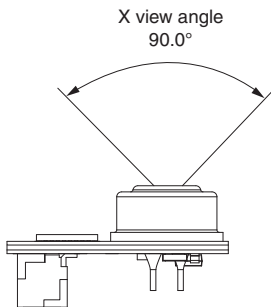
### Detection Area for Each Pixel



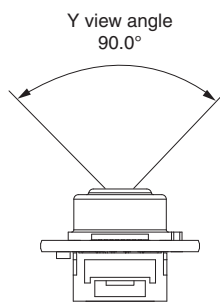
Note: Definition of view angle: Using the maximum Sensor output as a reference, the angular range where the Sensor output is 50% or higher when the angle of the Sensor is changed is defined as the view angle.

## D6T-32L-01A

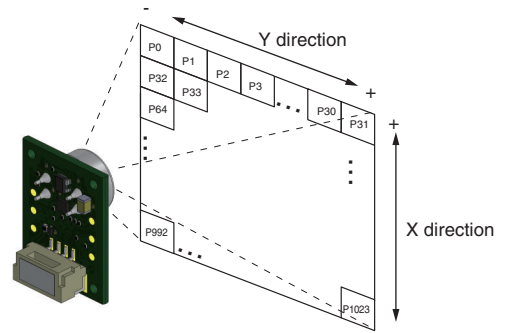
### Field of view in X Direction



### Field of view in Y Direction



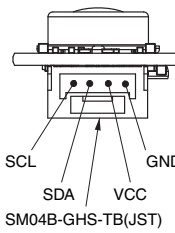
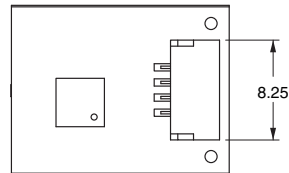
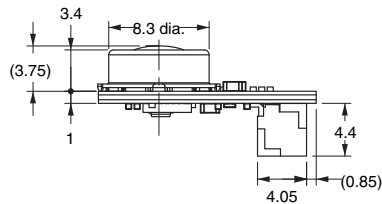
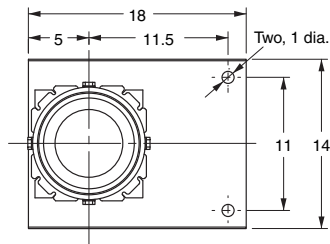
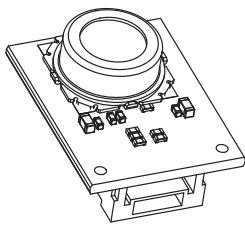
### Detection Area for Each Pixel



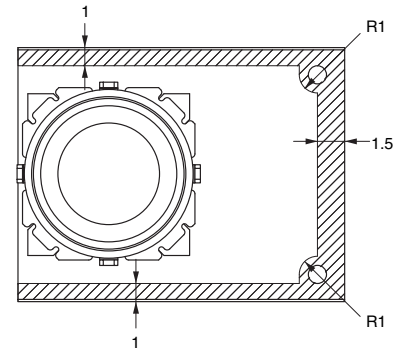
Note: Definition of view angle: Using the maximum Sensor output as a reference, the angular range where the Sensor output is 50% or higher when the angle of the Sensor is changed is defined as the view angle.

## Dimensions (Unit: mm)

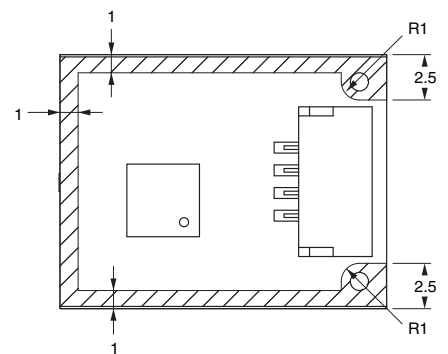
### D6T-44L-06/06H



Supporting and Mounting Area (Shaded Portion)  
Top View

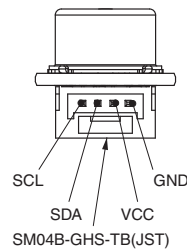
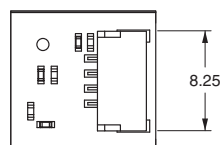
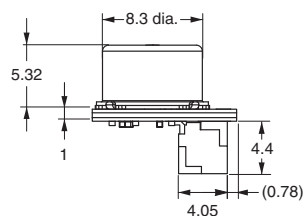
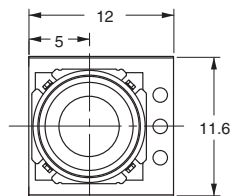
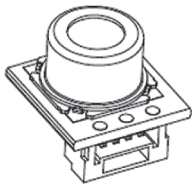


Bottom View

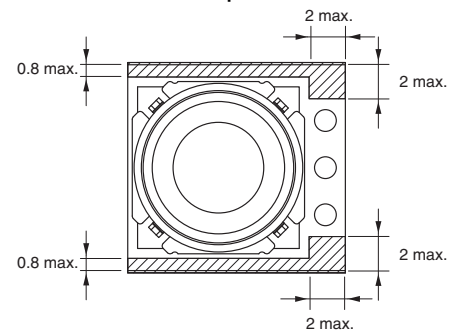


Note: Due to insulation distance limitations, do not allow metal parts to come into contact with the Sensor.

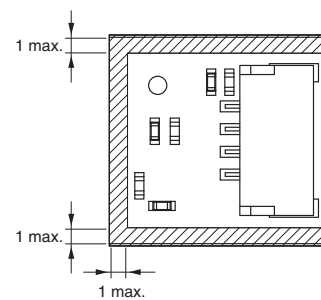
### D6T-8L-09/09H



Supporting and Mounting Area (Shaded Portion)  
Top View



Bottom View

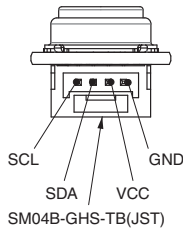
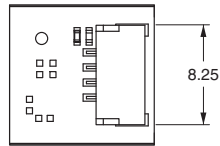
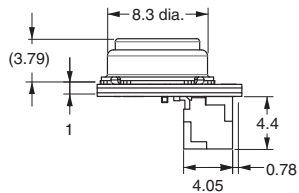
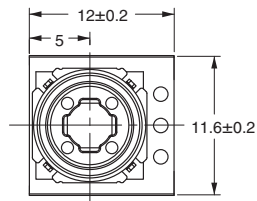
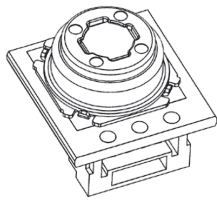


Note: Due to insulation distance limitations, do not allow metal parts to come into contact with the Sensor.

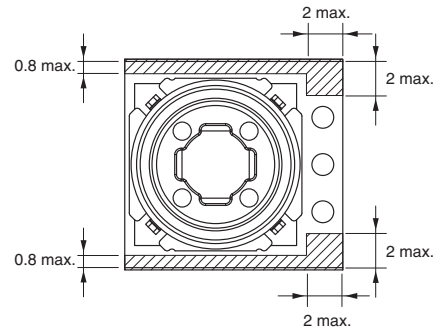
Note: Unless otherwise specified, a tolerance of  $\pm 0.3$  mm applies to all dimensions.



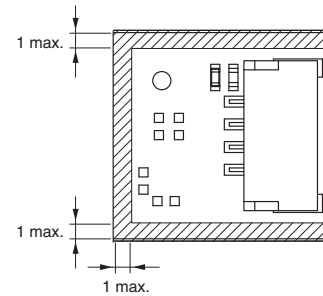
## D6T-1A-01/02



Supporting and Mounting Area (Shaded Portion)  
Top View



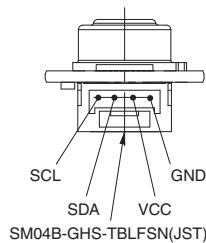
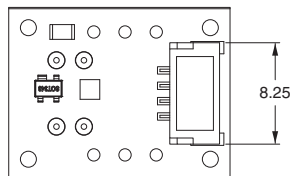
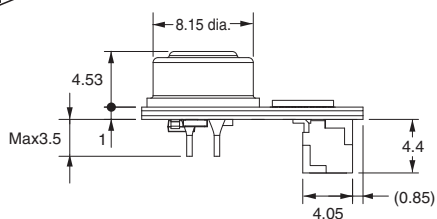
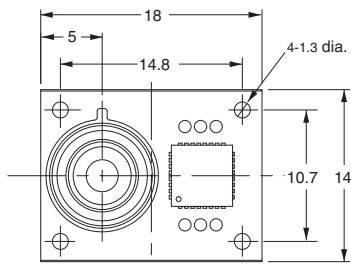
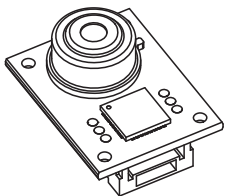
Bottom View



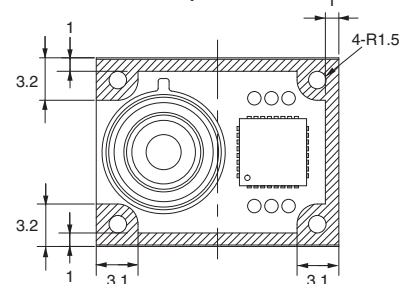
Note: Due to insulation distance limitations, do not allow metal parts to come into contact with the Sensor.

## D6T-32L-01A

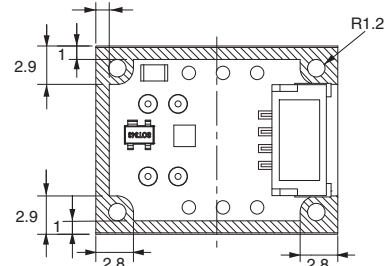
D6T



Supporting and Mounting Area (Shaded Portion)  
Top View



Bottom View



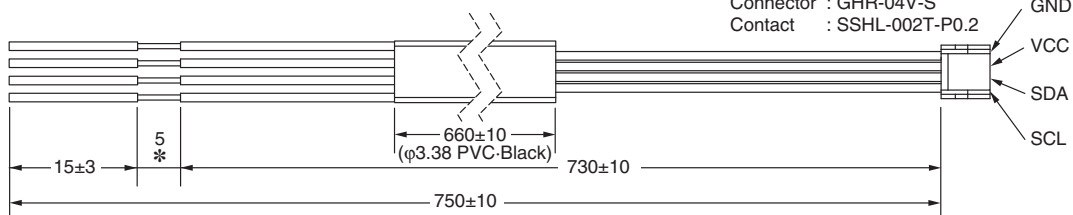
Note: Due to insulation distance limitations, do not allow metal parts to come into contact with the Sensor.

## D6T-HARNESS-02 (Optional - sold separately)

### Cable Color

GND → BLACK Wire  
VCC → RED Wire  
SDA → BLUE Wire  
SCL → YELLOW Wire

\* Length of Cable removed sheath.



Cable :UL1061.AWG#28  
UL Tube : T-105-2 No.8  
Connector : GHR-04V-S  
Contact : SSSL-002T-P0.2

Note: Unless otherwise specified, a tolerance of  $\pm 0.3$  mm applies to all dimensions.

## Safety Precautions

### Precautions for Correct Use

#### ● Installation

- The Sensor may not achieve the characteristics given in this datasheet due to the ambient environment or installation location. Before using the Sensor, please acquire an adequate understanding and make a prior assessment of Sensor characteristics in your actual system.

#### ● Operating Environment

- Do not use the Sensor in locations where dust, dirt, oil, and other foreign matter will adhere to the lens. This may prevent correct temperature measurements.
- Do not use the Sensor in any of the following locations.
  - Locations where the Sensor may come into contact with water or oil
  - Outdoors
  - Locations subject to direct sunlight.
  - Locations subject to corrosive gases (in particular, chloride, sulfide, or ammonia gases).
  - Locations subject to extreme temperature changes
  - Locations subject to icing or condensation.
  - Locations subject to excessive vibration or shock.

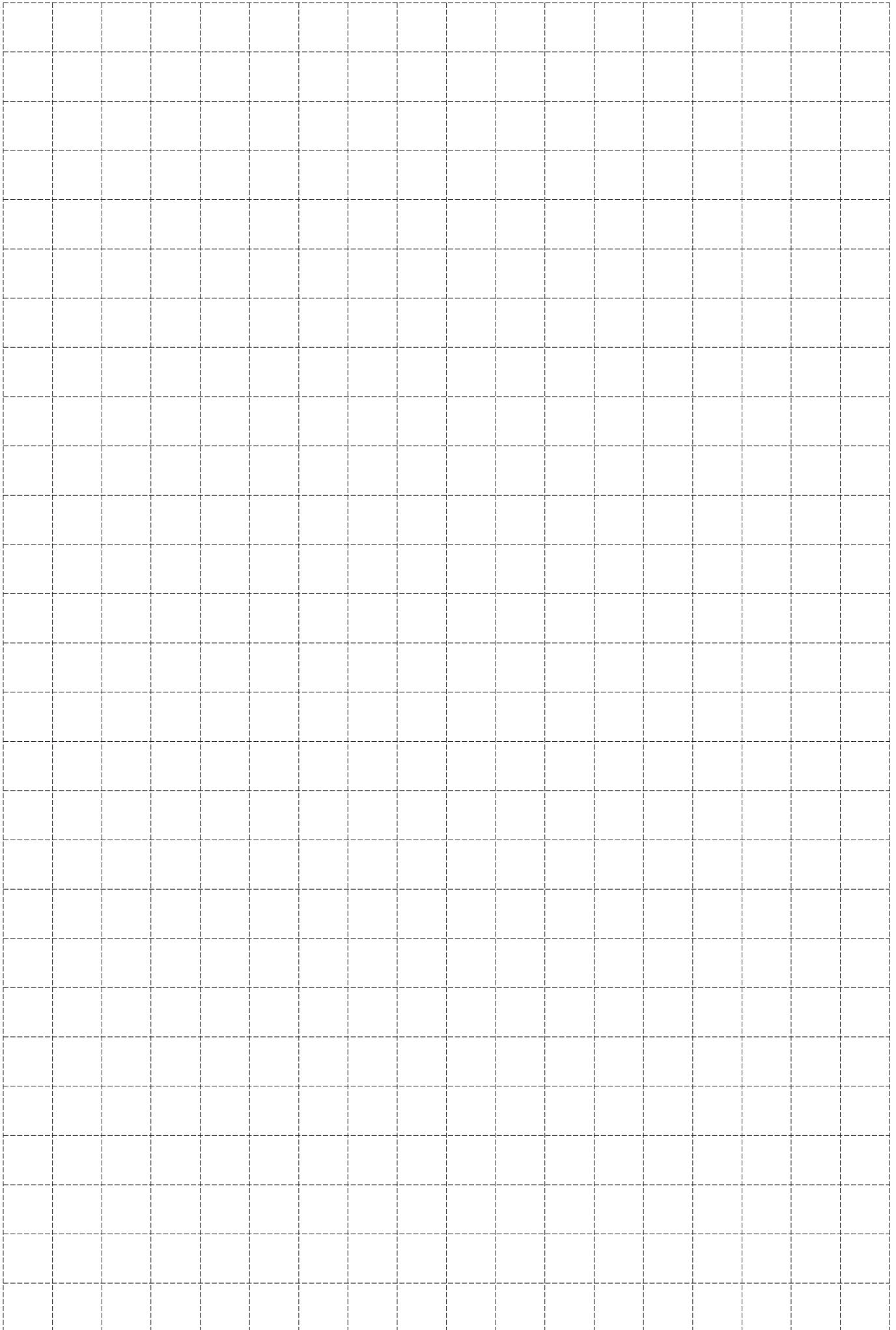
#### ● Noise Countermeasures

- The Sensor does not contain any protective circuits. Never subject it to an electrical load that exceeds the absolute maximum ratings for even an instance. The circuits may be damaged. Install protective circuits as required so that the absolute maximum ratings are not exceeded.
- Keep as much space as possible between the Sensor and devices that generates high frequencies (such as high-frequency welders and high-frequency sewing machines) or surges.
- Attach a surge protector or noise filter on nearby noise-generating devices (in particular, motors, transformers, solenoids, magnetic coils, or devices that have an inductance component).
- In order to prevent inductive noise, separate the connector of the Sensor from power lines carrying high voltages or large currents. Using a shielded line is also effective.
- If a switching regulator is used, check that malfunctions will not occur due to switching noise from the power supply.

#### ● Handling

- This Sensor is a precision device. Do not drop it or subject it to excessive shock or force. Doing so may damage the Sensor or change its characteristics. Never subject the connector to unnecessary force. Do not use a Sensor that has been dropped.
- Take countermeasures against static electricity before you handle the Sensor.
- Turn OFF the power supply to the system before you install the Sensor. Working with the Sensor while the power supply is turned ON may cause malfunctions.
- Secure the Sensor firmly so that the optical axis does not move.
- Install the Sensor on a flat surface. If the installation surface is not even, the Sensor may be deformed, preventing correct measurements.
- Do not install the Sensor with screws. Screws may cause the resist to peel from the board. Secure the Sensor in a way that will not cause the resist to peel.
- Always check operation after you install the Sensor.
- Use the specified connector (GHR-04 from JST) and connect it securely so that it will not come off. If you solder directly to the connector terminals, the Sensor may be damaged.
- Make sure to wire the polarity of the terminals correctly. Incorrect polarity may damage the Sensor.
- Never attempt to disassemble the Sensor.
- Do not use the cable harness to the other product.





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